

Angles in standard position with the same terminal side are co-terminal angles.
 Co-terminal angles are important because the trigonometric ratios regarding co-terminal angles are equivalent.

Example: Give two co-terminal angles for each given angle, one positive and one negative.

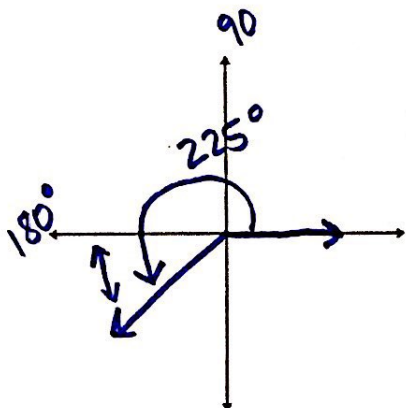
1. 65° 2. 540° 3. $\frac{13\pi}{18}$ 4. $\frac{14\pi}{9}$

$65 + 360 = \boxed{425^\circ}$ $540 - 360 = \boxed{180^\circ}$ $\frac{13\pi}{18} + 2\pi = \boxed{\frac{49\pi}{18}}$ $\frac{14\pi}{9} + 2\pi = \boxed{\frac{32\pi}{9}}$
 $65 - 360 = \boxed{-295^\circ}$ $540 - 360 - 360 = \boxed{-180^\circ}$ $\frac{13\pi}{18} - 2\pi = \boxed{-\frac{23\pi}{18}}$ $\frac{14\pi}{9} - 2\pi = \boxed{-\frac{4\pi}{9}}$

A reference angle is the angle that the terminal side makes with the "closest" part of the x-axis. Reference angles are important because they allow us to utilize right angle trigonometry on the rotational system. To determine a reference angle for an angle in standard position, compare the angle's measure to the closest X-axis. You will either need to subtract using a multiple of 180 or π if you are in quadrant II or III or multiple of 360 or 2π if you are in quadrant IV.

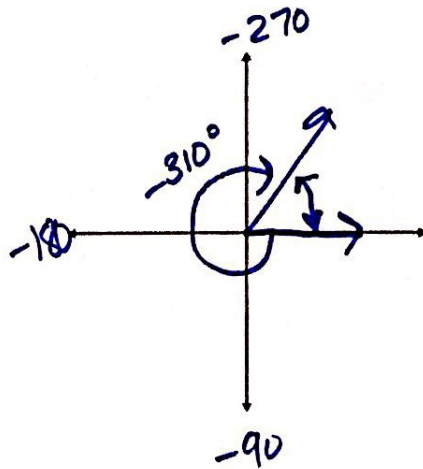
Example: Sketch and find the reference angles for each angle.

5. 225°



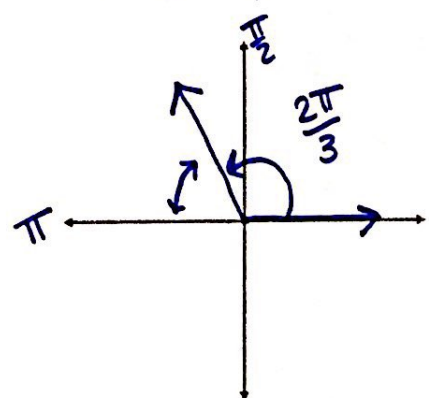
Ref. $225 - 180$
 $\boxed{45^\circ}$

6. -310°



Ref.
 $-310 + 360 = \boxed{50^\circ}$

7. $\frac{2\pi \cdot 2}{3 \cdot 2} = \frac{4\pi}{6}$



Ref: $\pi - \frac{2\pi}{3} =$
 $\boxed{\frac{\pi}{3}}$